

1. Recall Shortest Path problems

SS All DEST

S.S. S. DEST

etc.

Assume we have a weighted directed graph. (can have negative wts.)

we consider the Bellman-ford Algorithm what is the idea?

Relax all edges  $(V-1)$  times

what is Relax? if  $d[v] > d[u] + w(u,v)$   
replace.

Relax( $u, v, w$ )

1. if  $d[v] > d[u] + w(u,v)$
2.  $d[v] \leftarrow d[u] + w(u,v)$ .

Bellman-ford ( $V, E, s$ )

1.  $d[v] \leftarrow \infty \quad \forall v \in V$
2.  $d[s] \leftarrow 0$
3. for  $i \leftarrow 1$  to  $|V|-1$ .
4. for each edge  $(u,v) \in E$
5. Relax( $u, v, w$ ).

Running Time?  $\Theta(VE)$

for a dense graph?  $\Theta(V^3)$ .

If we do the Relaxation of <sup>all</sup> edges / many times  
what can we determine? NWC.

Suppose we have a DAG (no cycles).

here we can get the order in which to relax the edges by a topological sort.

if  $v_1$  is before  $v_2$  before  $v_3$  before  $v_4$  in the topological sort, (Recall lecture from Mon 11/5). 2 WEEKS AGO.

what do we know about graph  $G$ ?

We know  $\nexists$  an edge from  $v_2$  to  $v_1$  or  $v_3$  to  $v_2$  or  $v_3$  to  $v_1$ , etc.

Recall: TOP. SORT  $\Rightarrow$  if  $(u,v) \in E$  then  $u$  comes before  $v$  in the top. order.

If we relax in topological order, we will get the shortest paths

1. TOPOLOGICAL SORT	$\Theta(V+E)$	] algorithm for shortest paths in a DAG
2. Relax edges in top. order	$\Theta(V+E)$	
	$\Theta(V+E)$	

Expand 2.

2.1.  $d[v] \leftarrow \infty$  if  $v \in V$

2.2.  $d[s] \leftarrow 0$

2.3 for each  $u$  in TOP order

2.4 for each  $v$  adj to  $u$

2.5 relax( $u,v,w$ ).

Recall Relax( $u,v,w$ )

1. if  $d[v] > d[u] + w(u,v)$

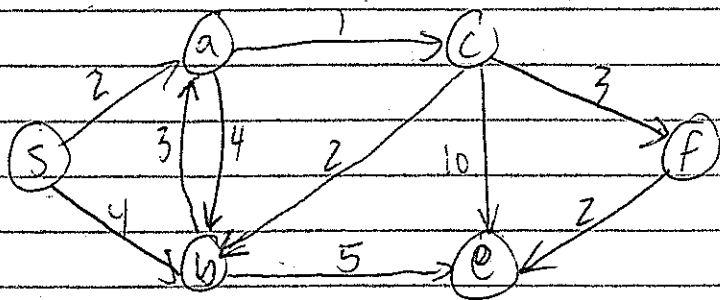
2.  $d[v] \leftarrow d[u] + w(u,v)$

Recall Dijkstra's algorithm from CS226.

What D.S. does Dijkstra's use? What problem does it solve?

SSS? on weighted, directed graph (w/ non-neg. weights)

so  $w(u,v) \geq 0 \forall (u,v)$  edges.



PUT ALL IN PQ.

we'll also keep track of predecessor.

	PRED
<del>S, 0</del>	NIL
<del>a, 2</del>	S
<del>b, 4</del>	S
<del>c, 3</del>	a
<del>e, 13</del>	b
<del>f, 6</del>	c

CAN MAINTAIN PQ as an array of d's

S	a	b	c	e	f
0	<del>∞</del>	<del>∞</del>	<del>∞</del>	<del>∞</del>	<del>∞</del>
	2	4	3	<del>13</del>	6
				9	
				8	

We extract min, get S, 0. look@ 2 edges

both reduce  $\infty \rightarrow 2$  &  $\infty \rightarrow 4$  decrease keys on both update predecessors of a, b to S.

extract min to get a, 2 (now S & a are done).  
consider  $a \rightarrow b$  &  $a \rightarrow c$   $4 \neq 4+2$ ,  $\infty > 2+1$ .

for 11-28-2018

for SP. algorithm we have. for Directed Weighted Graphs:

1. BELLMAN-FORD : EDGES CAN BE NEGATIVE  
Relax <sup>all</sup> edges  $V-1$  times  $\Rightarrow \Theta(V \cdot E)$   
can determine NWC if go one more time & changes NO CYCLES,
2. DAG-SHORTEST-PATHS : REQUIRES ~~DAG~~, NEG WTS OK.  
TOP SORT  
RELAX in that order.  $\Rightarrow \Theta(V + E)$

3. DIJKSTRA'S : REQUIRES WT NONNEG.

Similar to PRIM'S.

What did PRIM'S ALGORITHM SOLVE?

KRUSKAL'S SOLVED IT TOO?

MST on undirected, weighted, connected graph.

DO YOU RECALL D.S. PRIM'S USED?

PQ

DIJKSTRA'S DOES TOO.

Show 237, 238, 248, 251, 252, 253, 254, 255, 256, 257, 258

Dijkstra's is similar to Prim's for MST but Prim's doesn't ADD the weights.

Dijkstra's  $(V, E, s)$

1.  $d[v] \leftarrow \infty \forall v \in V$
2.  $d[s] \leftarrow 0$
3. Build a PQ on the d's
4. while PQ not empty
5.  $u \leftarrow \text{PQ.ExtractMin}()$
6. for each  $v$  adj to  $u$
7. if  $d[v] > d[u] + w(u, v)$
8. decrease key  $(v, d[u] + w(u, v))$
9.  $v.\text{pred} \leftarrow u$

Prim's doesn't do this.

Running Time?

1-3  $\Theta(V)$

4-9 happens  $V$  times

have  $V$  ExtractMins

6-9 goes  $E$  total times so we have  
 $E$  Decrease Keys.

So just find Prim's RUNNING TIME depends on PQ implementation

	PQ UNSORTED ARRAY	PQ BIN. HEAP	PQ FIB. HEAP (Amortized)
V Extr. Min	$V \cdot O(V)$	$V \cdot O(\lg V)$	$V \cdot O(\lg V)$
E DecreaseKey	$E \cdot O(1)$	$E \cdot O(\lg V)$	$E \cdot O(1)$
	$O(N^2 + E)$	$O(V \lg V + E \lg V)$	$O(V \lg V + E)$
	$= O(V^2)$	if connected = $O(E \lg V)$	
	<del><math>O(N^2 + E)</math></del> b/c E is $O(1)$		

DENSE	prefer	Unsorted Array	b/c	$E \approx V^2$
SPARSE	"	BIN. HEAP	b/c	$E \approx V$
MEDIUM	"	FIB. "		

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Let's consider solutions to ALL-PAIRS S.P. problem

How can we use the Single Source S.P. algorithms to solve?

Any ideas?

Assume Adj. List for edges (not adj. mtrx).

Recall:

Bellman Ford  $\Theta(VE)$

Dijkstra's  $\Theta(V^2 + E)$  using F.b. Heap for PA.

Can do Repeated B-F. (once for each source  $v$ )  
so  $\Theta(V^2E)$

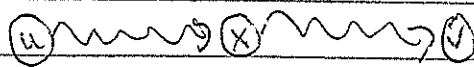
Can do Repeated Dijkstra's (if no neg. wts.)  $\Theta(V^2 + VE)$

We want to come up w/ something better (in terms of time) than those.

Consider an Adj. Matrix for these instead of Adj. List

Dynamic Programming Problems can often be formulated as shortest path graph problems.

S.P.'s



If  $u \dots y$  is a S.P. that goes through  $x$

then  $u \dots x$  is shortest &  $x \dots y$  is shortest

$\Rightarrow$  OPTIMAL SUBSTRUCTURE